

A Lightweight Dataflow Approach for Design and Implementation of SDR Systems

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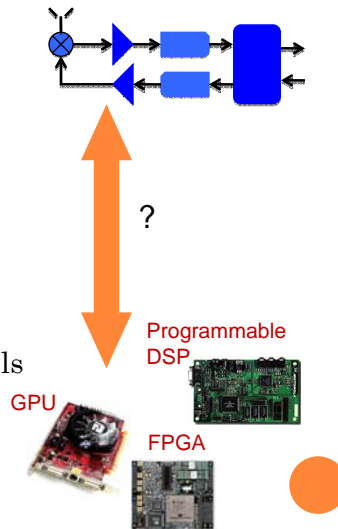


OUTLINE

- Introduction
- Background
- Dataflow-based Design Flow
- Lightweight Dataflow Programming Approach
- Design Example
- Conclusion and Future Work

INTRODUCTION

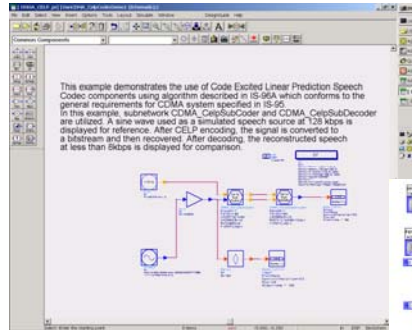
- In SDR, designers attempt to
 - Implement most of the complex signal handling of radio using software
 - Rapidly target a variety of platforms (retargetability)
- In modern, complex systems we would like to
 - Create an application description independent of the targeted platform
 - Interface with a diverse set of tools
 - Arrive at an initial prototype quickly
 - Achieve high performance, less resource usage



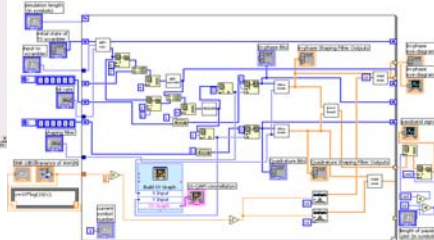
MODEL-BASED DESIGN BASED ON DATAFLOW MODEL OF COMPUTATION

- Dataflow-based design is a specific form of *model-based design*
 - i.e., high level application subsystems are specified in terms of components that interact through formal models of computation
- Dataflow model of computation
 - Used widely in design tools for DSP
 - Used widely for expressing the functionality of DSP applications
 - Application is modeled as a directed graph
 - Data-driven execution model
 - Iterative execution

EXAMPLE: DATAFLOW-BASED DESIGN TOOLS FOR DSP



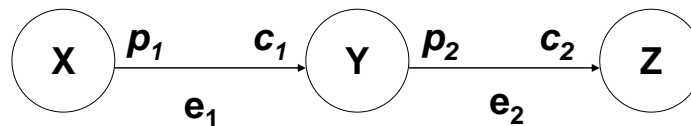
Example from Agilent ADS tool



Example from National Instruments LabVIEW

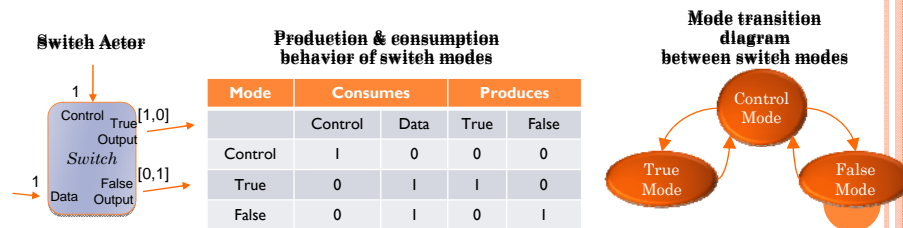
DATAFLOW GRAPHS AND SEMANTICS

- Vertices (actors) represent computation
- Edges represent FIFO buffers
- Edges may have delays, implemented as initial tokens
- Tokens are produced and consumed on edges
- Different models have different rules for production and consumption (SDF=fixed, CSDF=periodic, BDF=dynamic)



EXAMPLE. CORE FUNCTIONAL DATAFLOW (CFDF) MODEL OF COMPUTATION

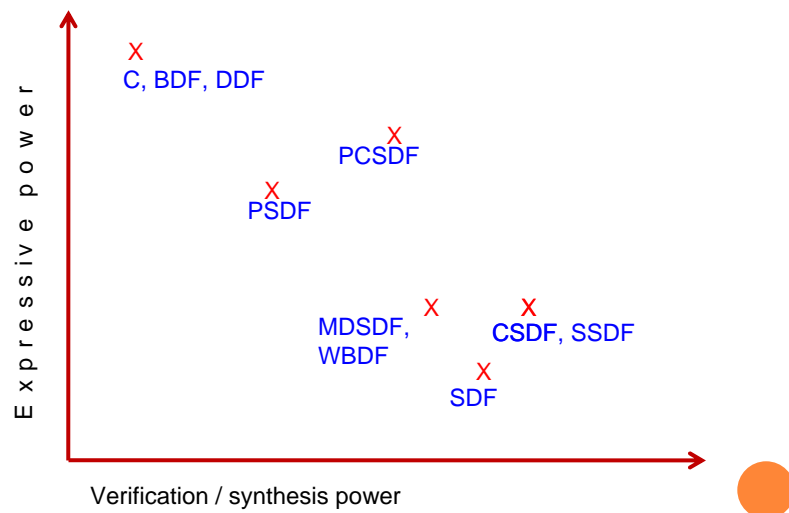
- Divide actors into a set of *modes*
 - Each mode has a fixed consumption and production behavior, but actors may dynamically switch between modes.
- Write the enabling conditions for each mode
- Write the computation associated with each mode
 - Including next mode to *enable* and then *invoke*
- For example, consider a standard Switch:



EVOLUTION OF DATAFLOW MODELS OF COMPUTATION FOR DSP: EXAMPLES

- Computation Graphs and Marked Graphs [Karp 1966, Reiter 1968]
- Synchronous dataflow, [Lee 1987]
 - Static multirate behavior
 - SPW (Cadence), National Instruments LabVIEW, and others.
- Well behaved stream flow graphs [1992]
 - Schemas for bounded dynamics
- Boolean/integer dataflow [Buck 1994]
 - Turing complete models
- Multidimensional synchronous dataflow [Lee 1992]
 - Image and video processing
- Scalable synchronous dataflow [Ritz 1993]
 - Block processing
 - COSSAP (Synopsis)
- CAL [Eker 2003]
 - Actor-based dataflow language
- Cyclo-static dataflow [Bilsen 1996]
 - Phased behavior
 - Eonic Virtuoso Synchro, Synopsis El Greco and Cocentric, Angeles System Canvas
- Bounded dynamic dataflow
 - Bounded dynamic data transfer [Pankert 1994]
- The processing graph method [Stevens, 1997]
 - Reconfigurable dynamic dataflow
 - U. S. Naval Research Lab, MCCI Autocoding Toolset
- Stream-based functions [Kienhuis 2001]
- Parameterized dataflow [Bhattacharya 2001]
 - Reconfigurable static dataflow
 - Meta-modeling for more general dataflow graph reconfiguration
- Reactive process networks [Geilen 2004]
- Blocked dataflow [Ko 2005]
 - Image and video through parameterized processing
- Windowed synchronous dataflow [Keinert 2006]
- Parameterized stream-based functions [Nikolov 2008]
- Enable-invoke dataflow [Plishker 2008]
- Variable rate dataflow [Wiggers 2008]

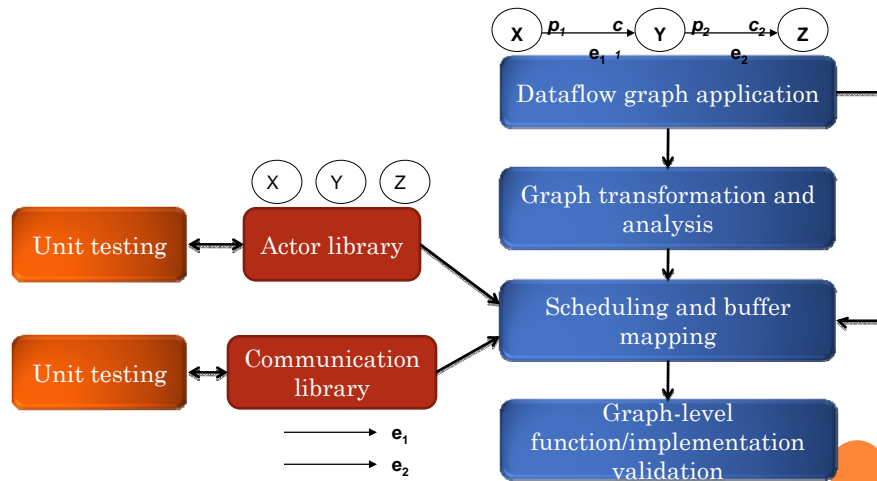
MODELING DESIGN SPACE OF DATAFLOW



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DESIGN FLOW



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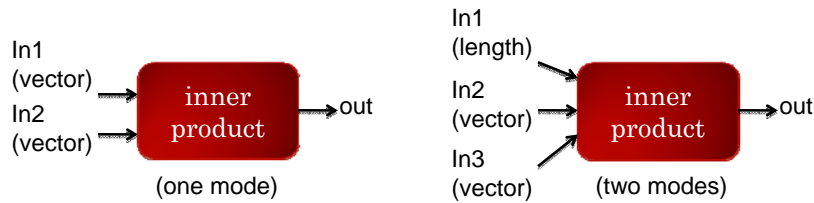
LIGHTWEIGHT DATAFLOW PROGRAMMING APPROACH

- LWDF
- A dataflow programming approach for model-based design and implementation of DSP systems.
 - By “lightweight”: minimally intrusive on existing design processes, and require minimal dependence on specialized tools or libraries.
- Features
 - Improve the **productivity** of the design process and the quality of derived implementations.
 - **Retargetability** across different platforms.
 - Allow designers to **integrate and experiment with dataflow modeling approaches** relatively quickly and flexibly into existing design methodologies and processes.

LWDF DESIGN PRINCIPLES I

- Each actor has an operational context (OC), which encapsulates
 - parameters
 - mode/status variables
 - local variables
 - references to the FIFOs
 - corresponding to the input and output ports of the actor as a component of the enclosing dataflow graph.
 - reference to the execution functions of the actor.

OPERATIONAL CONTEXT – EXAMPLE OF LWDF-C



```

typedef struct {
    /* parameters */
    int length;

    /* mode variable */
    int mode;

    /* refs to the FIFOs */
    fifo_pointer in1;
    fifo_pointer in2;
    fifo_pointer out;

    /* refs to the execution functions*/
    actor_enable_function_type enable;
    actor_invoke_function_type invoke;
} inner_product_context_type;
  
```

```

typedef struct {
    /* local variables */
    int length;

    /* mode variable */
    int mode;

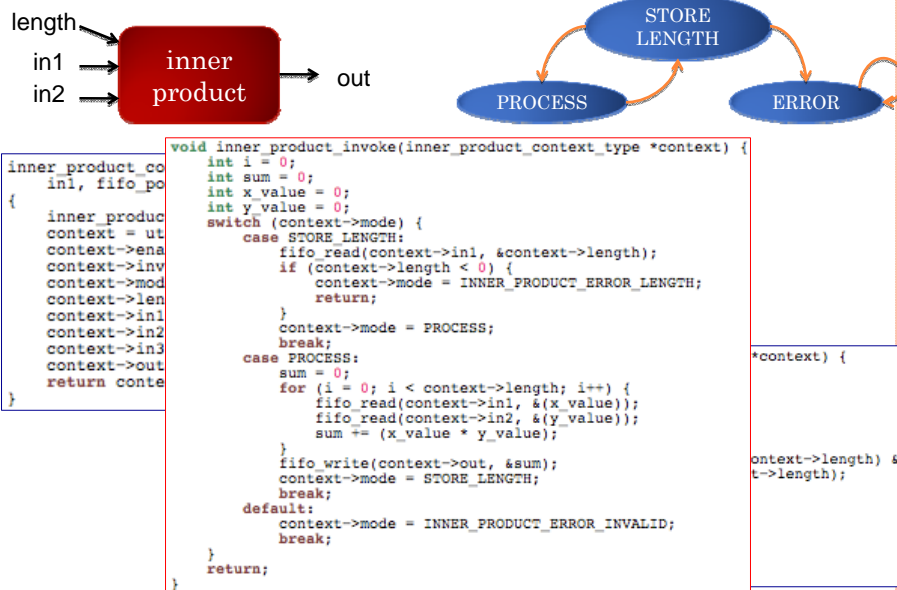
    /* refs to the FIFOs */
    fifo_pointer in1;
    fifo_pointer in2;
    fifo_pointer in3;
    fifo_pointer out;

    /* refs to the execution functions*/
    actor_enable_function_type enable;
    actor_invoke_function_type invoke;
} inner_product_context_type;
  
```

LWDF DESIGN PRINCIPLES II

- Methods that are involved for the implementation of an actor
 - **Construct**: connects an actor to its input and output edges (FIFO channels), and performs any other pre-execution initialization associated with the actor.
 - **Execute**: implements the operational semantics of a dataflow model associated with an actor firing.
 - e.g. enable and invoke functions of CFDF
 - **Terminate**. performs any operations that are required for "closing out" the actor after the enclosing graph has finished executing

METHODS – EXAMPLE OF LWDF-C



ACTOR APIS IN LWDF-C

Type Definitions:

/* An actor's operational context (OC). */

```

typedef struct {
    /* parameters */
    /* local and mode variables */
    /* references to FIFO pointers */
    /* reference to a pointer of actor's execution functions */
} [actor_name]_context_struct;
    
```

/* A pointer to actor enable/invoke functions, which are functions that executes an actor with a given context. */

```

typedef void (*actor_[enable/invoke]_function_type) (struct
    actor_context_struct *context);
    
```

Key Methods:

```

[actor_name]_context_type *[actor_name]_new(...);
void [actor_name] enable([actor_name]_context_type *context);
void [actor_name] invoke([actor_name]_context_type *context);
void [actor_name] terminate([actor_name]_context_type *context);
    
```

ORTHOGONALIZING DATAFLOW COMMUNICATION: FIFO

- Each data item in the FIFO is referred to as a "token", and tokens can have arbitrary types associated with them.
- For a given FIFO instance, there is a fixed token size (number of bytes per token).
- Tokens have arbitrary types
 - e.g., integers, floating point values (float or double), characters, or pointers (to any kind of data).

FIFO APIS IN LWDF-C

Type Definitions:

```
/* A FIFO. */  
typedef struct _fifo_struct fifo_type;  
/* A pointer to a fifo. */  
typedef fifo_type *fifo_pointer;
```

Key Methods:

```
fifo_pointer fifo_new(int capacity, int token_size);  
int fifo_population(fifo_pointer fifo);  
int fifo_capacity(fifo_pointer fifo);  
void fifo_write(fifo_pointer fifo, void *data);  
void fifo_write_block(fifo_pointer fifo, void *data, int size);  
void fifo_read(fifo_pointer fifo, void *data);  
void fifo_read_block(fifo_pointer fifo, void *data, int size);
```

IMPLEMENTATION IN VERILOG

- LWDF-V
- Dataflow actor -> Verilog module
 - This module can contain arbitrary sub-modules for complex actors
 - This module can be behavioral or structural
 - Actor port -> module port
 - Actor constructor -> module instantiation
- Step/Mode transition graph -> FSM within actor
 - Controls actor execute function
 - One or more concurrent processes that make up the steady-state behavior of the actor

EXAMPLE: IMPLEMENTATION TEMPLATE IN LWDF-V

```
//Verilog structural modeling
//Instantiation of the step transition controller
actor_controller fsm(post_list);

`include "actor_modules.v"
`include "libs.v"

/* Common actor steps */
`define FS 4'b0001

/* Number of steps */
`define STEP_COUNT 4

`define S2 4'b0010
`define S3 4'b0100
`define FD 4'b1000

module actor_name(port_list);
//parameters
parameter ...
//output and input ports
output ...
input ...

//internal registers and wires

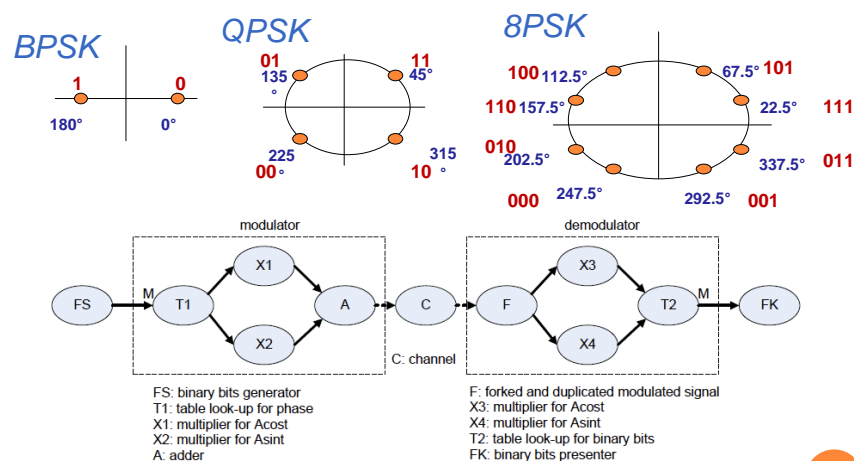
//Verilog behavior modeling
always@(posedge clock) begin
//sequential logics based on step transition
case (state)
`FS:
`S2:
`S3:
`FD:
endcase
end

always@(*) begin
//combinational logics based on step transitions
case (state)
`FS:
`S2:
`S3:
`FD:
endcase
endmodule
```

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DESIGN EXAMPLE: RECONFIGURABLE PHASE-SHIFT KEYING



- M=1 for BPSK, M=2 for QPSK, and M=3 for 8PSK

DESIGN EXAMPLE II.

RECONFIGURABLE PHASE-SHIFT KEYING

LWDF-C implementation for the table-lookup actor in RPSK

```
#include <stdio.h>
#include <stdlib.h>

#include "table_lookup.h"
#include "util.h"

table_lookup_context_type *table_lookup_new(file *file, int size,
disps_fifo_pointer in, disps_fifo_pointer out) {
    table_lookup_context_type *context = null;
    float data = 0;
    int i = 0;

    if (size <= 0) {
        printf(stderr, "table_lookup_new error: invalid size");
        exit(1);
    }
    context = util_malloc(sizeof(table_lookup_context_type));
    context->table = util_malloc(size * sizeof(int));
    context->size = size;
    context->execute = (actor_execution_function_type)table_lookup_execute;

    for (i = 0; i < size; i++) {
        if (fscanf(file, "%f", &data) != 1) {
            printf(stderr, "table_lookup_new error: integer expected");
            exit(1);
        }
        (context->table)[i] = data;
    }

    context->status = actor_new_firing;
    context->in = in;
    context->out = out;

    return context;
}

void table_lookup_execute(table_lookup_context_type *context) {
    float result = 0;

    switch (context->status) {
        case actor_new_firing:
            if (disps_fifo_population(context->in) == 0) {
                return;
            }
            disps_fifo_read(context->in, &(context->index));

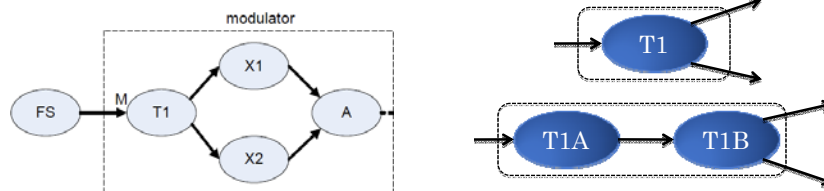
            if (((context->index) < 0) || ((context->index) >= (context->size))) {
                context->status = TABLE_LOOKUP_ERROR_INDEX;
                return;
            }

            context->status = TABLE_LOOKUP_INDEX_READ;
            /* falls through */
        case TABLE_LOOKUP_INDEX_READ:
            if (disps_fifo_population(context->out) >=
                disps_fifo_capacity(context->out)) {
                return;
            }
            result = (context->table)[context->index];
            disps_fifo_write(context->out, &result);
            context->status = ACTOR_FIRING_DONE;
            /* falls through */
        case ACTOR_FIRING_DONE:
            return;
        default:
            context->status = TABLE_LOOKUP_ERROR_ENTRY;
            break;
    }
}
```

DESIGN EXAMPLE II.

RECONFIGURABLE PHASE-SHIFT KEYING

Graph topology designed in LWDF-C (i.e., example of RPSK modulator)



```
actors[ACTOR_BINARY_SIGNAL_SOURCE] = (actor_context_type *) (file_source_new(in_file, fifo2));
actors[ACTOR_PSK_PACK] = (actor_context_type *) (psk_pack_new(fifo1, fifo2, fifo3));
actors[ACTOR_TABLE_LOOKUP] = (actor_context_type *) (table_lookup_new(table_file, table_size,
fifo3, fifo4));
actors[ACTOR_FORK] = (actor_context_type *) (fork_new(fifo4, fifo5, fifo6));
actors[ACTOR_CARRIER_FREQ_MUL1] =
(actor_context_type *) (carrier_freq_mul_new(CARRIER_FREQ_MUL_TYPE_FORWARD,
CARRIER_FREQ_TYPE_COS, INIT_AMPLITUDE, CARRIER_FREQ, COS_SIGN,
DEMODULATE_PTS, fifo5, fifo7));
actors[ACTOR_CARRIER_FREQ_MUL2] = (actor_context_type *)
(carrier_freq_mul_new(CARRIER_FREQ_MUL_TYPE_FORWARD, CARRIER_FREQ_TYPE_SIN,
INIT_AMPLITUDE, CARRIER_FREQ, SIN_SIGN, DEMODULATE_PTS, fifo6, fifo8));
actors[ACTOR_PSK_ADD] = (actor_context_type *) (psk_add_new(500e-6, fifo7, fifo8, fifo9));
actors[ACTOR_FILE_SINK] = (actor_context_type *) (file_sink_float_new(out_file, fifo9));
```

DESIGN EXAMPLE: RECONFIGURABLE PHASE-SHIFT KEYING

Application simulation driven by a simple scheduler

```
void util_simple_scheduler(actor_context_type *actors[], int actor_count,
char *descriptors[]) {
    boolean progress = FALSE;
    int i = 0;
    do {
        progress = 0;
        for (i = 0; i < actor_count; i++) {
            progress |= util_guarded_execution(actors[i], descriptors[i]);
        }
    } while (progress);
}
```

→ guarded execution for CFDF model

○ Simulation based on LWDF-C

- 3GHz Intel Pentium PC with 2GB of RAM
- Input bit stream: 10,000 bits
- Simulation time: 1.5 seconds

DESIGN EXAMPLE: RECONFIGURABLE PHASE-SHIFT KEYING

Graph topology designed in LWDF-V (i.e., example of RPSK modulator)

```
file_source #(.DATA_WIDTH(DATA_WIDTH), .IN_FILE(IN_FILE)) fs_module1(.out(fifo1_in), .write(fifo1_write),
.out_full(fifo1_full), .clock(clock), .reset(reset), .enable_firing_reset(1'b1));
psk_table_lookup #(.BLOCK_SIZE(BLOCK_SIZE), .INPUT_DATA_WIDTH(DATA_WIDTH),
.OUTPUT_DATA_WIDTH(DATA_WIDTH), .COUNTER_WIDTH(COUNTER_WIDTH)) psk_table_lookup_module (.out(fifo2_in),
.read(fifo2_read), .write(fifo2_write), .in(fifo1_out), .in_empty(fifo1_empty), .out_full(fifo2_full), .clock(clock), .reset(reset),
.enable_firing_reset(1'b1));

actor_fork #(.DATA_WIDTH(DATA_WIDTH)) fork_module (.out1(fifo3_in), .out2(fifo4_in), .read(fifo2_read),
.write(fifo3_4_write), .in(fifo2_out), .in_empty(fifo2_empty), .out1_full(fifo3_full), .out2_full(fifo4_full), .clock(clock), .reset(reset),
.enable_firing_reset(1'b1));

multiplier #(.INPUT_DATA_WIDTH(DATA_WIDTH), .OUTPUT_DATA_WIDTH(DATA_WIDTH)) mul_module1 (.out(fifo5_in),
.read(fifo3_read), .write(fifo5_write), .in1(fifo3_out), .in2(1), .in1_empty(fifo3_empty), .in2_empty(0), .out_full(fifo5_full),
.clock(clock), .reset(reset), .enable_firing_reset(1'b1));

multiplier #(.INPUT_DATA_WIDTH(DATA_WIDTH), .OUTPUT_DATA_WIDTH(DATA_WIDTH)) mul_module2 (.out(fifo6_in),
.read(fifo4_read), .write(fifo6_write), .in1(fifo4_out), .in2(1), .in1_empty(fifo4_empty), .in2_empty(0), .out_full(fifo6_full),
.clock(clock), .reset(reset), .enable_firing_reset(1'b1));

add #(.DATA_WIDTH(DATA_WIDTH)) add_module (.out(fifo7_in), .read(fifo5_6_read), .write(fifo7_write), .in1(fifo5_out),
.in2(fifo6_out), .out_full(fifo7_full), .clock(clock), .reset(reset), .enable_firing_reset(1));

file_sink #(.DATA_WIDTH(DATA_WIDTH), .OUT_FILE(OUT_FILE)) fk_module(.read(fifo7_read), .in(fifo7_out),
.in_empty(fifo7_empty), .clock(clock), .reset(reset), .enable_firing_reset(1'b1));

fifo #(.DATA_WIDTH(DATA_WIDTH), .CAPACITY(CAPACITY), .PTR_WIDTH(PTR_WIDTH)) fifo_module1 (fifo1_out,
fifo1_full, fifo1_empty, fifo1_in, fifo1_read, fifo1_write, clock, clock, reset);
```

DESIGN EXAMPLE: RECONFIGURABLE PHASE-SHIFT KEYING

- Application execution driven by self-timed scheduling strategy
 - That is, an actor module fires whenever it has sufficient tokens available on its input FIFOs
- FPGA implementation based on LWDF-V
 - Target FPGA device: Xilinx Virtex-4
 - Resource utilizations after synthesis: 1,484 LUTs (5% util. rate) and 1,464 CLBs (10% util. rate)



CONCLUSION AND FUTURE WORK

- A lightweight dataflow programming approach for SDR systems
 - Simplified flow for design and testing
 - Well-structured design templates
- Retargetability: design and implementation in C and Verilog
 - Fast simulation, embedded software realization, and FPGA mapping
- Apply and experiment with various dataflow MoCs for more SDR applications



Thank You!

