



Exploiting the Link

**Improving CubeSat Communications through
the use of Software Defined Radios**

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University of Michigan
2009 SDR Forum

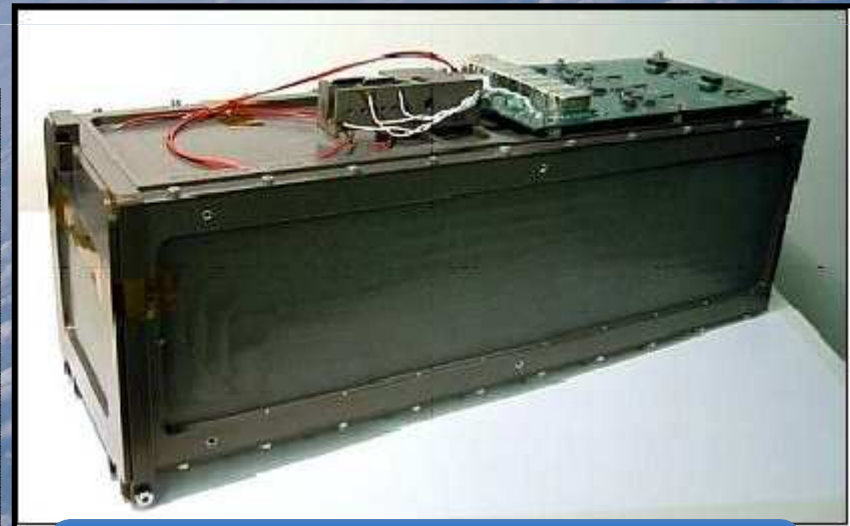
What is a CubeSat?



Cal Poly 1U Cubsat

- Formal specification satellite form factor and launch vehicle interface
 - Developed by Cal Poly (SLO) and Stanford in 1999
 - Simple, ~ 6 page document
 - International adoption of standard

- Basic Unit: 1U
 - Volume: 10x10x10cm
 - Mass: < 1kg
 - Power: 2W
 - Radios: amateur radio (U/VHF)
- Sizes
 - 1, 1.5, 2, 3 U
 - Power and capability scale



P-Pod – Flight qualified launch vehicle interface

Why a CubeSat?

- Initially, an educational tool
 - Hands on training for next generation of engineers and space scientists
 - Design, built, and launched within a student generation (< 4 years)
- First missions discovered several benefits
 - Certified launch vehicle interface—we're in a "safe" box
 - Design space is constrained—innovation ensues
 - Lower cost and faster missions
- Current on-orbit mission types
 - Educational
 - Technology demonstration
 - Science (space weather and remote sensing)
 - Communication

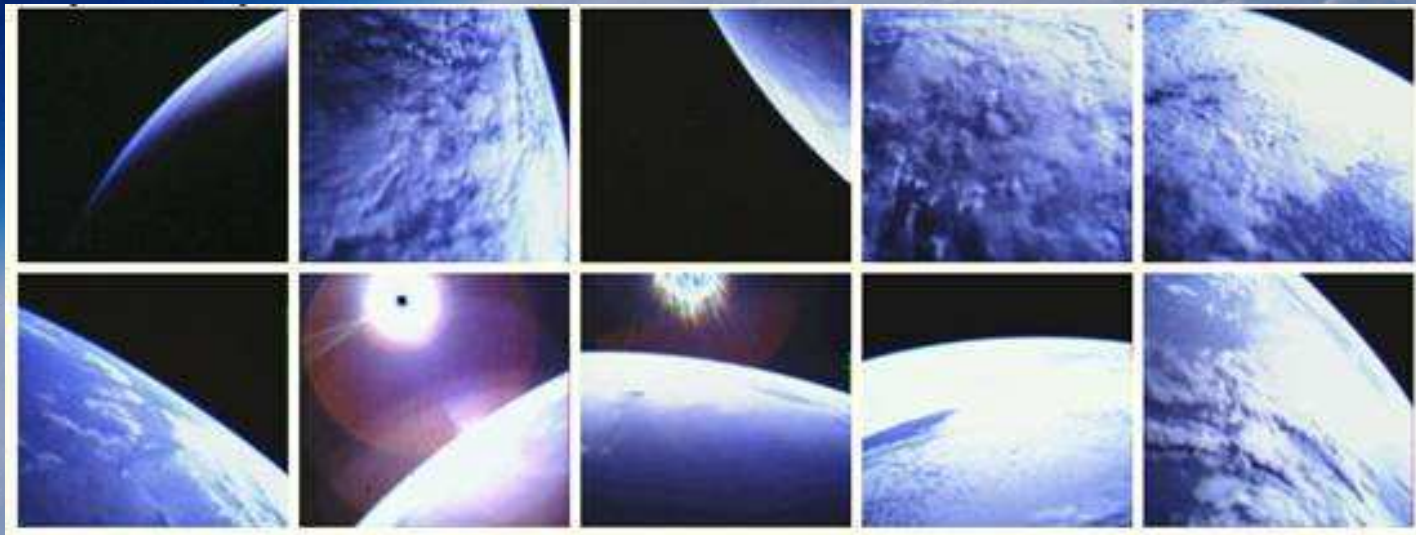
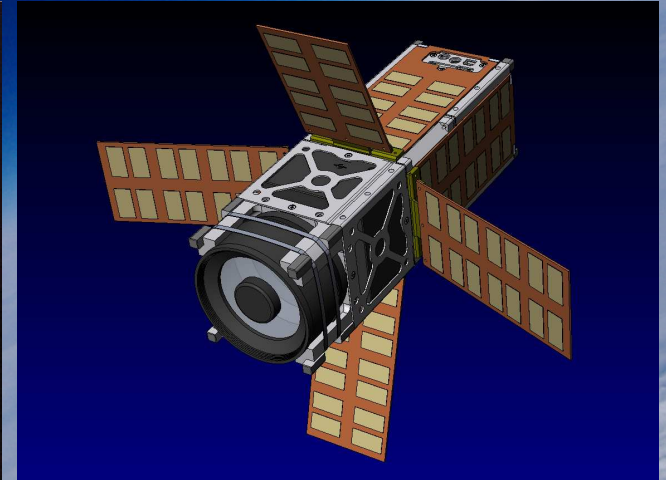
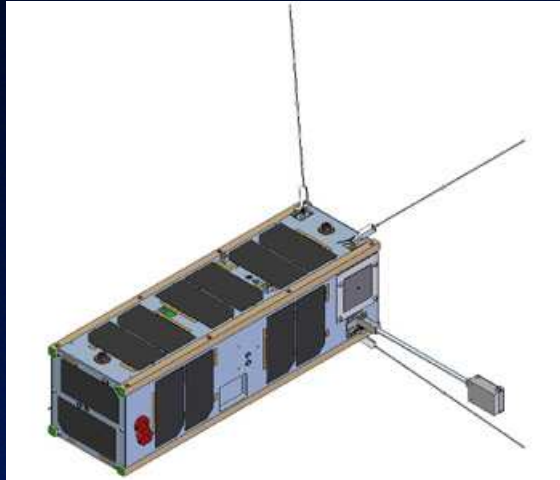


Numerous launches
of Cubesats.
Rockets from
Europe, India, US,
Japan

Who Uses Cubesats?

- Academia, Government, and Industry—International
- Educational groups
 - 100+ universities world wide
 - High schools
 - Amateur radio clubs
 - Middle school science fair project
- NSF has sponsored 5 space weather missions
 - First launches in 2010
- DoD has purchased 20+ systems
- Norway using for communication and ship tracking.
- The community is growing...

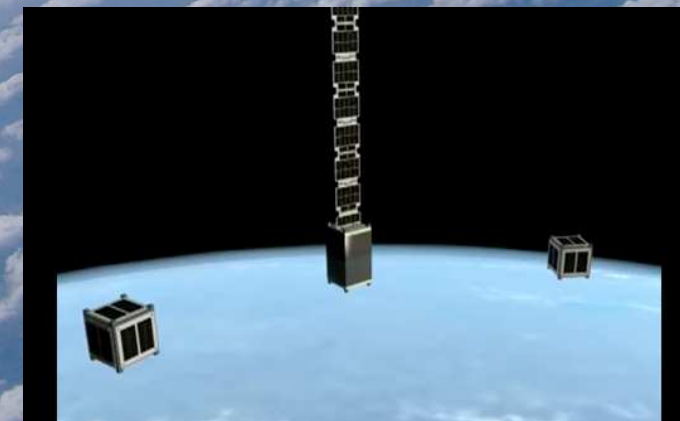
Example Missions



RAXLab Research Goals

Bold flight to extreme and remote environments.

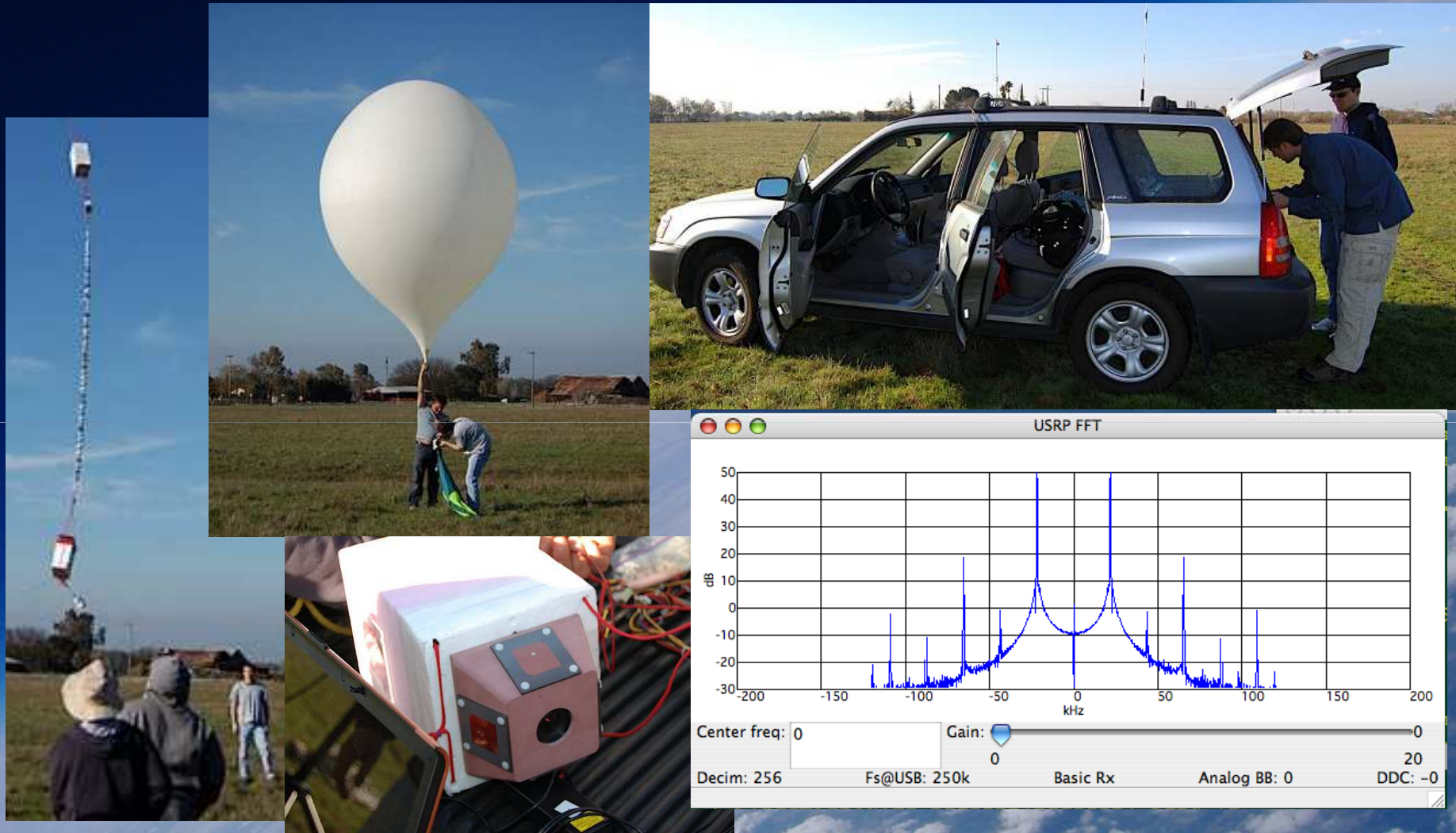
- Removing Communication as a constraint.
 - Can we talk to our space vehicles as easily as we access Google?
- Novel near space and space vehicles
 - Small (nano), maneuverable, capable satellites
 - Cooperative and self assembling
 - Frequency flights



Flight Opportunities



BioLaunch Field Work



Easy Recovery







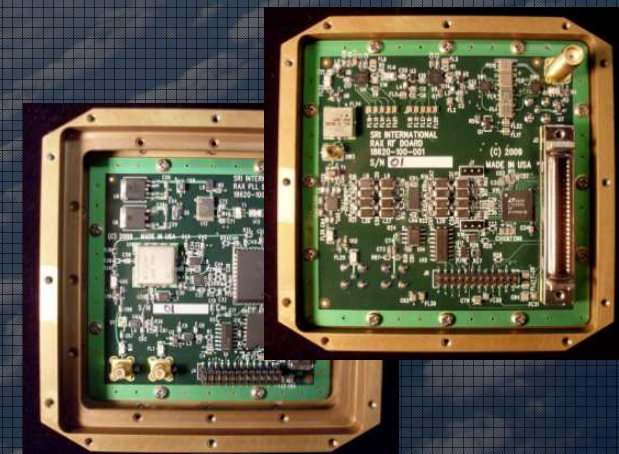
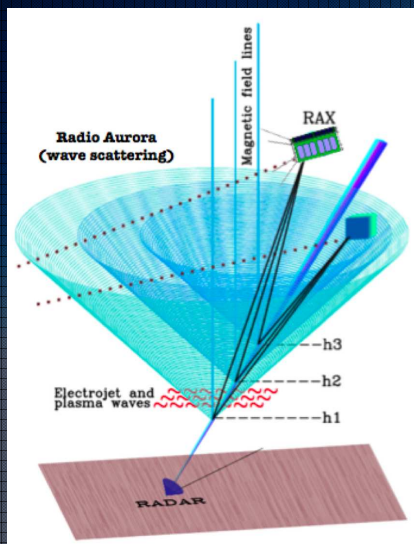
RAX—First NSF Sponsored Mission

- University of Michigan and SRI International Collaboration
- Co-investigators:
 1. Prof. James Cutler, University of Michigan
 2. Dr. Hasan Bahcivan, SRI International

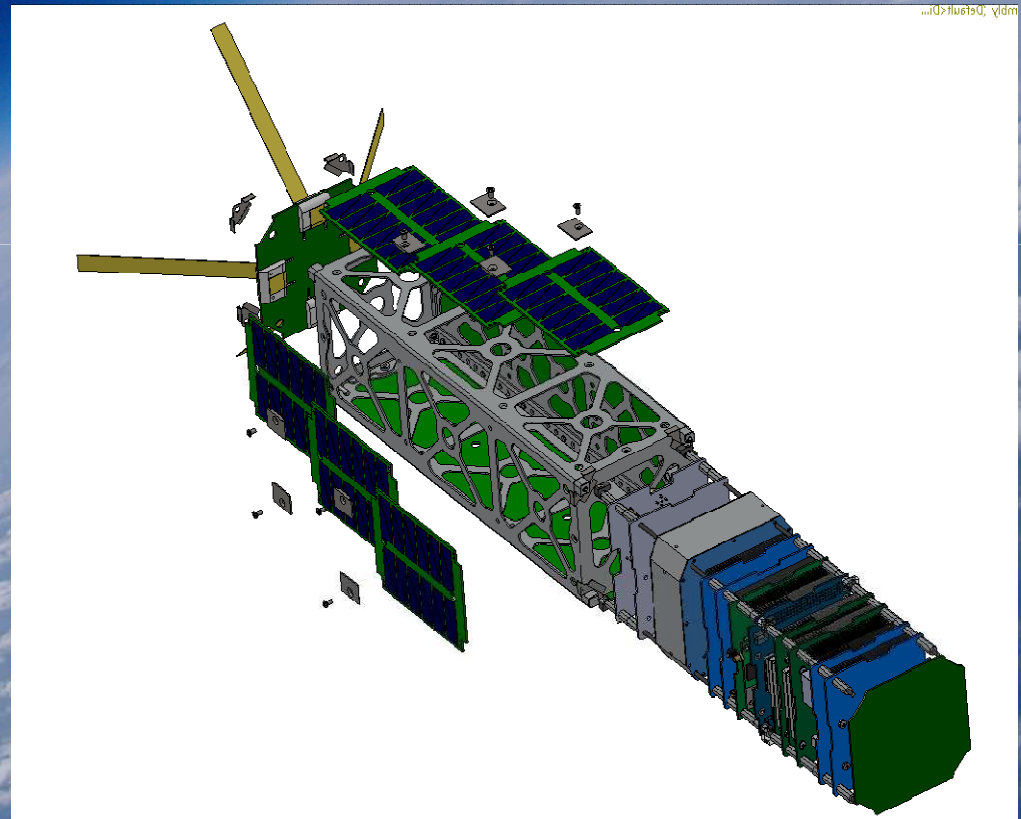
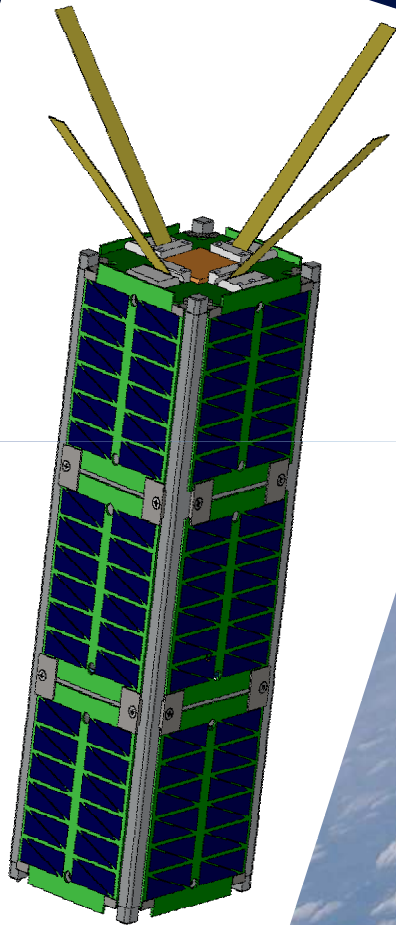


RAX Mission Objective:

Study formations and distribution of magnetic field-aligned plasma irregularities (FAI) located in the lower ionosphere



RAX System View

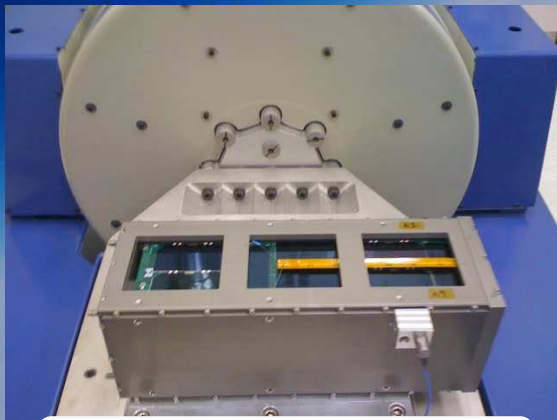


RAX Status

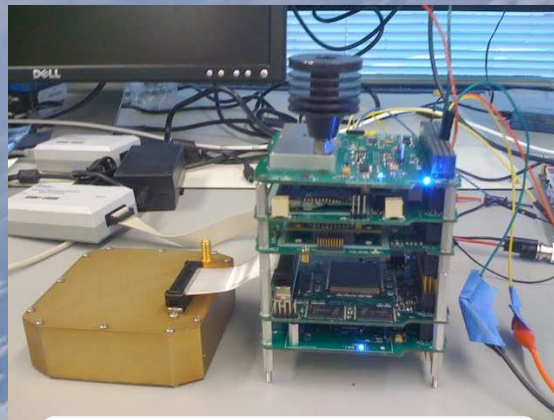
- Delivery date: ~2/2010
- Current RAX Work
 - Detailed characterization of engineering development units (EDU1 and EDU2)
 - Magnetic noise (attitude determination/control)
 - EMI and receiver noise
 - Attitude sensor calibration
 - Flight component fabrication
 - *Software, software, software*



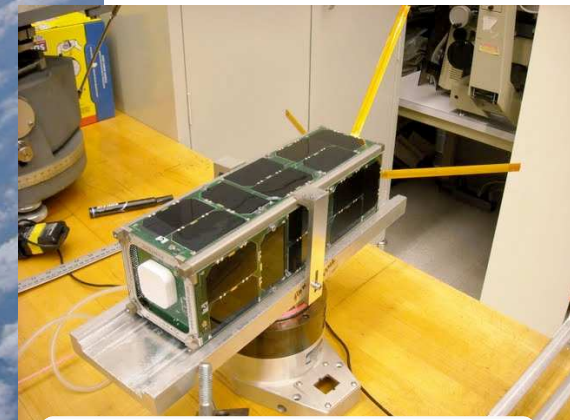
RAX EDU1 prior to
shake



RAX EDU1 shake test



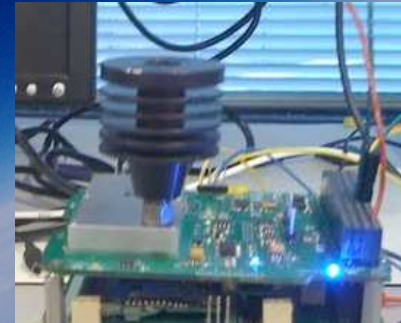
Mini stack for remote payload
operation and testing



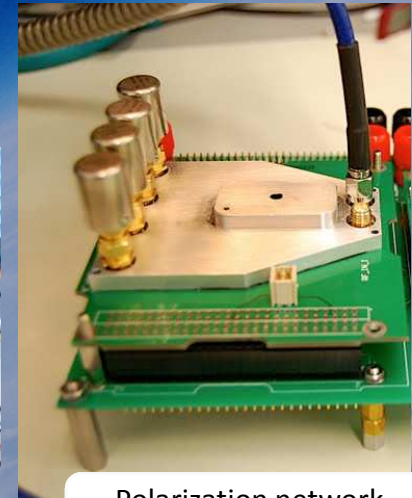
RAX inertia measurements @
70rpm

RAX Radios

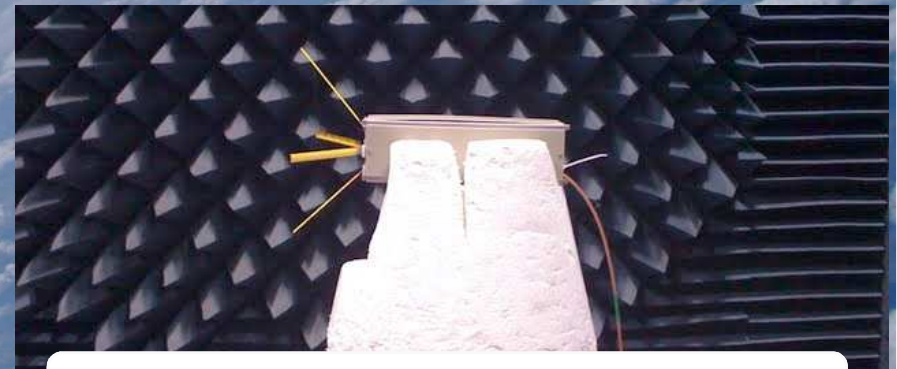
- Built our “own” UHF radio
 - Founded AstroDev with Kevin Brown while at Stanford.
 - Government funding to develop low-cost radios.
- Lithium-1 radio
 - ~140MHz – 600MHz.
 - Select 20MHz band at build time.
 - AX.25 packetization.
 - Configured for single band (dual possible).
 - Up to 40kbps like past AMSATs (though > 100kbps possible).
 - Independent of “bus” system architecture
- In House Antenna design
 - Turn stile with optimal orientation for radar signal reception.
- Polarization and antenna switch
 - Partnered with AstroDev to develop.
 - Polarization control: LHCP or RHCP
 - Antennas shared by both payload and transceiver.



Lithium integrated on our UHF and Watch Dog board



Polarization network and antenna switch



Initial anechoic chamber testing of the UHF antennas.

Cubesat Community Needs

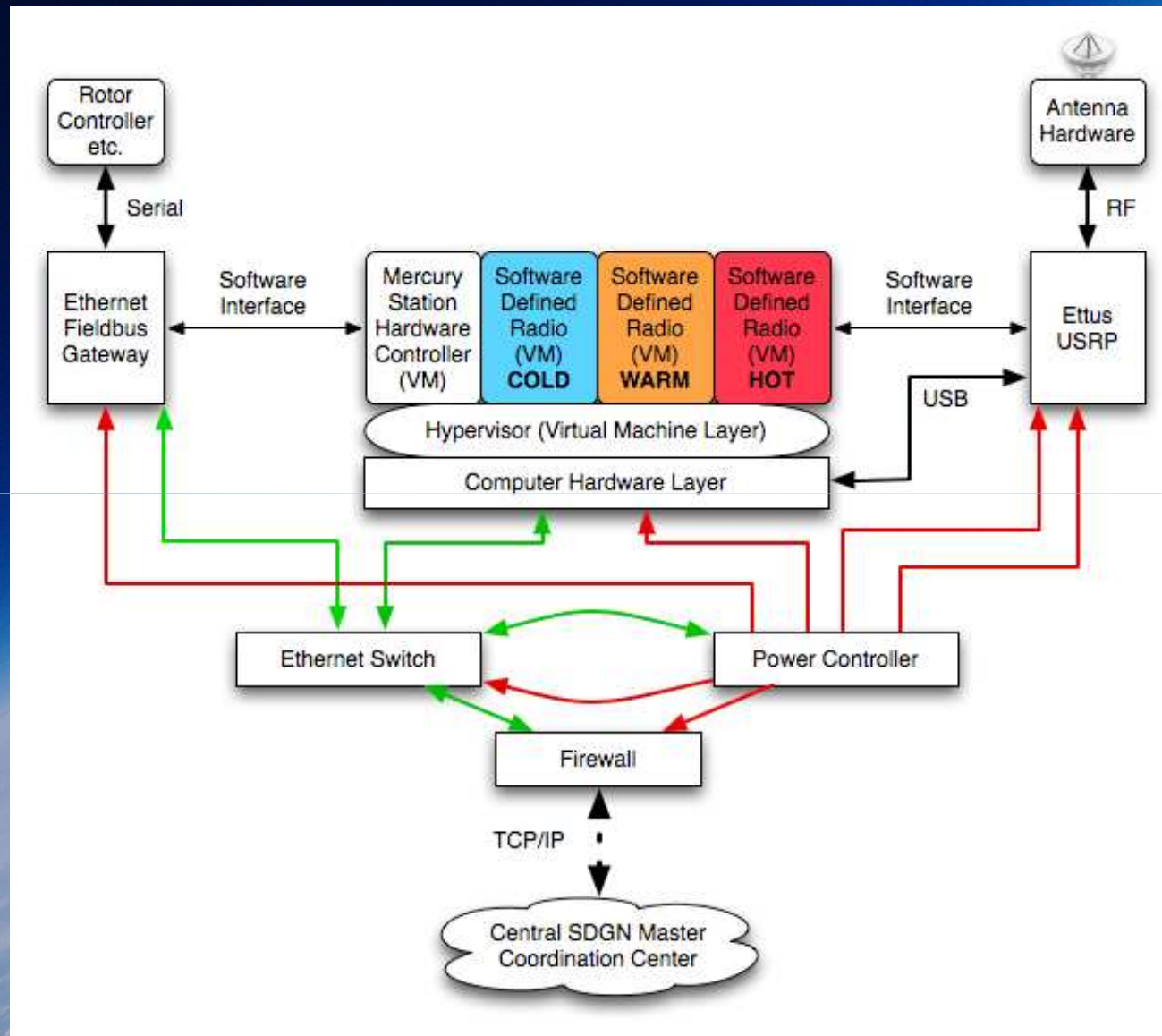
- In space – Resources constrained!
 - Low power, low mass, space environment
 - But large communication rates needed.
 - RAX is 1GB per day
- On the ground
 - Teams have limited stations
 - But there is a global network growing
- Specific needs and goals
 - ***Global ground station network*** with interoperable systems
 - Flexible communication systems to enable ***design operation***
 - ***Faster rates***
 - ***FCC Licensing***

Global Ground Stations

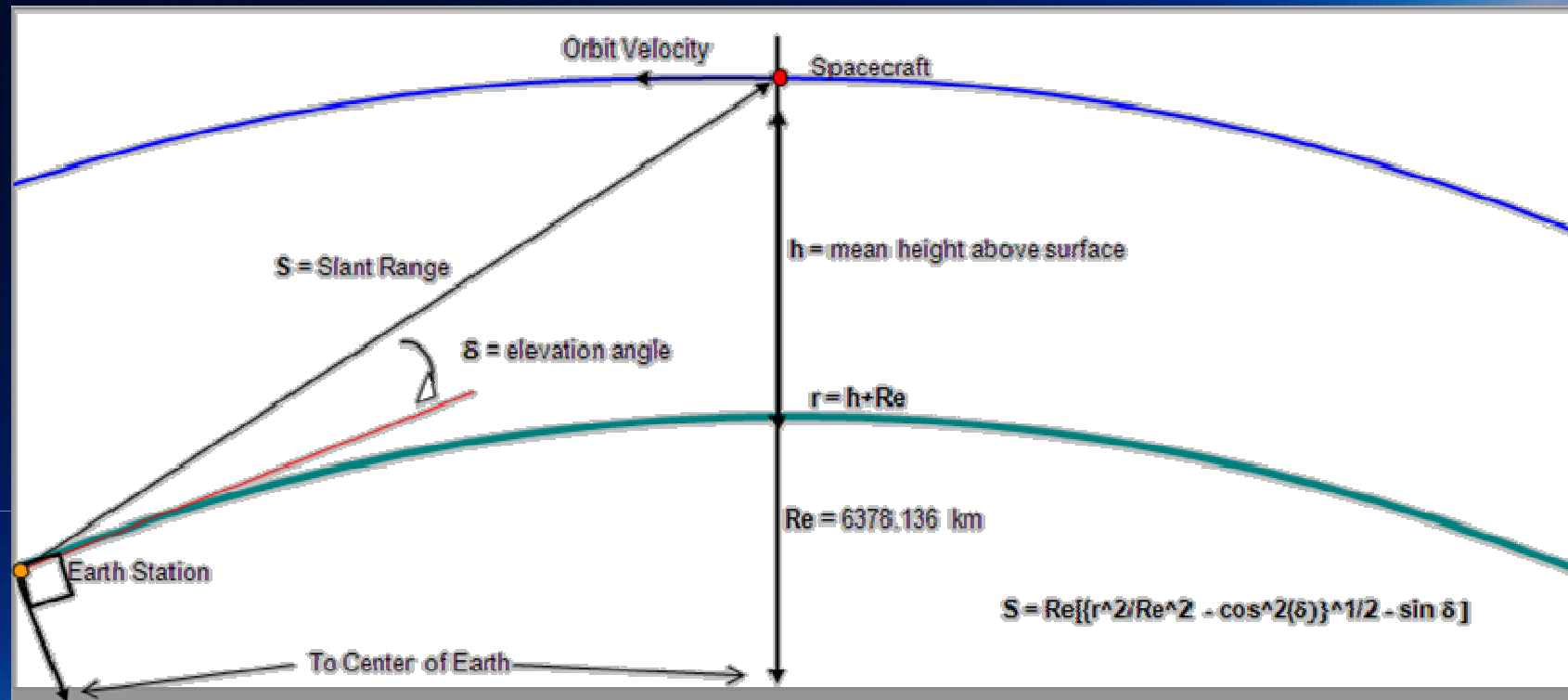


- Many ground stations, but little cooperation
- How do you measure and share capacity? How do you optimize schedule?

SDGS — Software Defined Ground Station



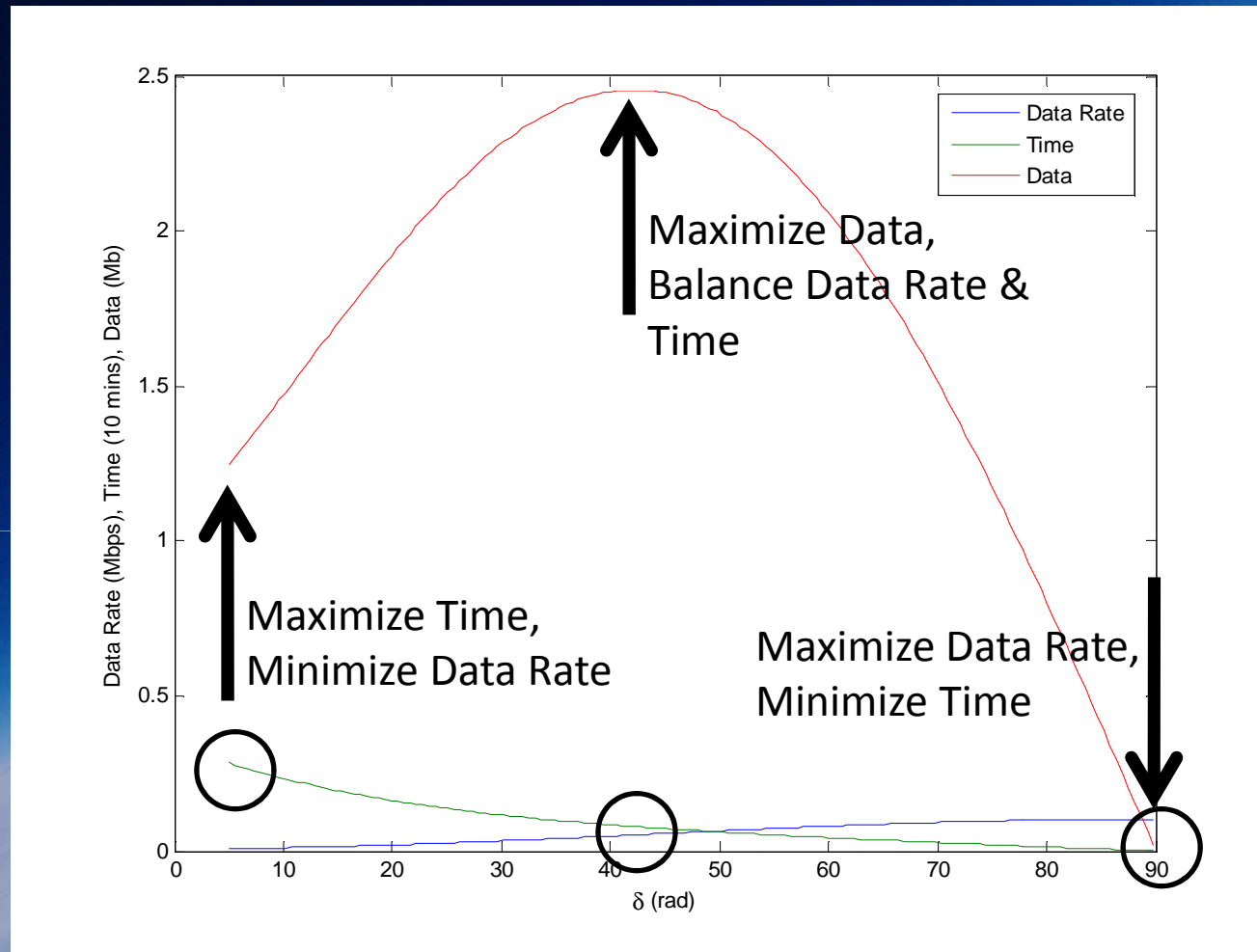
Communication Constraints



$$E_b/N_o = P + L_l + G_t + L_{pr} + L_s + L_a + G_r + 228.6 - 10 \log T_s - 10 \log R \quad (13-13)$$

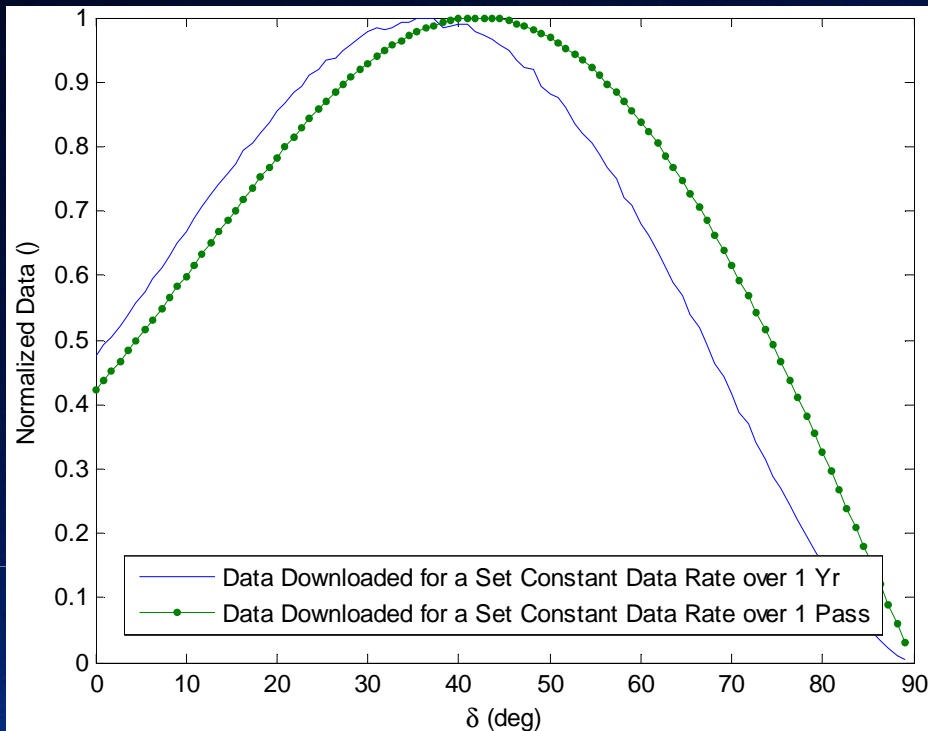
- Maximum data rate is proportional to range
- Lack of power constrains total data downlink
- Lack of radios available – especially small SDR

Better Design



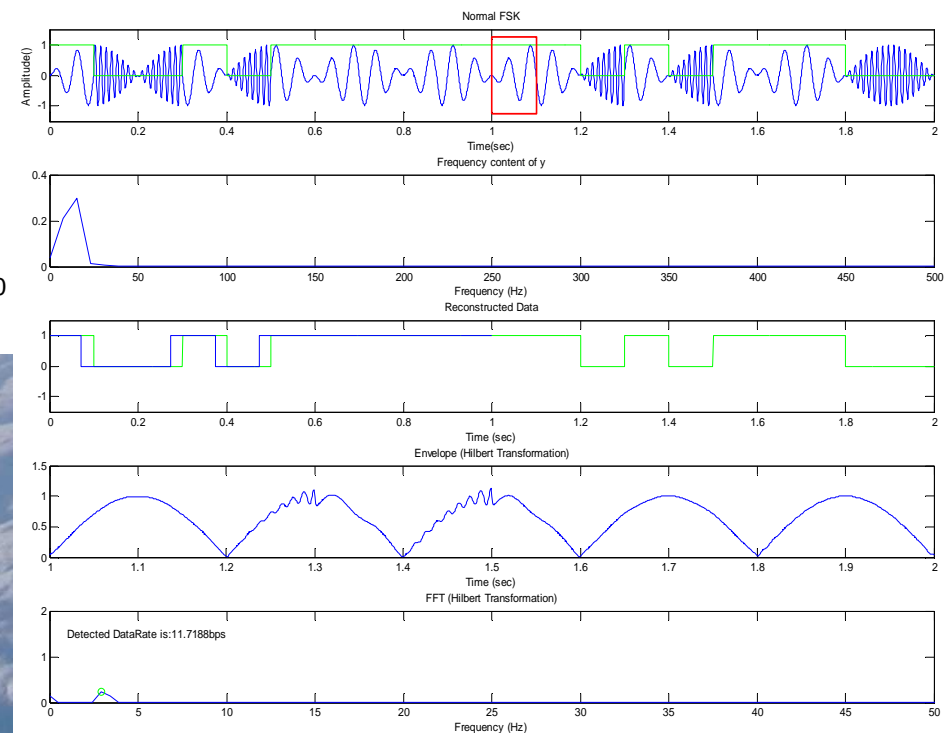
- Typical spacecraft use a fixed data rate for each pass that optimizes time
- What if we maximize data downloaded?

Better Utility



Optimize data rate based on pass characteristics (pre-set)

Optimize data rate dynamically
(self-clocking signals)



Frequency Licensing and Coordination

- In the past...
 - Most university and experimental missions have been classified as amateur radio satellites.
- Not a viable option as we move forward...
 - Government sponsored missions
 - Private industry
- So, what next?
 - Looking for spectral options
 - Possible 10MHz band 460 – 470 MHz. Low power density.
 - ISM – 2.4GHz
 - Other options? Share spectrum with existing satellite systems
- This will drive the radio technology selection and implementation

Conclusions

- CubeSats numbers are quickly growing
 - Exciting new missions
- Extremely constrained – Communication is challenging
 - We want to eliminate this constraint...
- Moving forward
 - FCC licensing
 - Groundstation networks
 - Optimal scheduling
 - Future proof...interoperability
 - Radios can be improved
 - Choose a smarter data rate
 - Extend **Software Defined Radios** to CubeSats
 - Choose dynamically changing data rates

Questions or Comments?

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